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- (4) Assume suitable additional data if necessary.
- 1. Answer any five of the following :- '
 - (a) Explain the terms 'Second breakdown' and 'SOAR' for power BJT.
 - (b) Draw turn-off-time characteristics for SCR and explain different mechanisms involved 4 in turn-off.
 - (c) Explain $\frac{dv}{dt}$ rating of SCR and explain reasons of its importance.
 - (d) Sketch torque speed characteristics of required cage induction motor in
 - (i) $\frac{V}{f}$ contrrol (ii) Stator voltage control
 - (e) Give techniques of electrical braking of separately excited d.c. motors.
 - (f) Compare voltage source inverters with current source inverters.

(a) Give practical methods to measure turn-off-time, $\frac{dv}{dt}$ rating, V_{AK} - breakover voltage of SCR. 8 2.

- (b) Explain effect of source inductance on performance of full converter. Draw relevent waveforms 8 in single phase and three phase circuits. 4
- (c) Give two methods of isolation between control circuit and power circuit.
- (a) With neat sketches of waveforms explain the working of full converter in (i) rectifier mode 10 3. (ii) inverter mode. Give conditions for successful inverting operation.
 - (b) The speed of 10 HP 220 V 1500 RPM dc motor armature is driven by 3 phase full converter. 10 The field current of motor is also controlled by another 3 phase full converter set to maximum output voltage. Armature resistance $R_a = 0.65$ Ohm, field resistance $R_f = 450$ Ohms, Motor constant K_v = 1.2 V/A-rad/sec. Assuming armature and field currents are continuous and ripple free, find
 - (i) Delay angle of armature converter at rated speed and rated power if input is 440 V 3 phase 50 Hz.
 - no load speed if armature current at no load is 10% of rated value. (ii)
- (a) Explain working of 3 phase bridge inverter in (1) 120 degrees mode and (ii) 180 degrees 10 4. mode using neat sketches of waveforms.
 - (b) Explain working of sinusoidal PWM inverter using relevent waveforms. Give advantages 10 of this inverter compared to single pulse inverter.
- (a) Draw circuit diagram of imulse commutated chopper using SCR's and explain its working 10 5. using important waveforms.

(b) A d.c. series motor is driven by Chopper using 300 V d.c. source $R_a = 0.05 \text{ Ohm}$ The armature resistance $R_{f} = 0.06 \text{ Ohm}$ $I_{a} = 500 \text{ Amps.}$ and field resistance The armature current Assuming armature current to be continuous and ripple free and duty cycle of chopper is 60% determine speed of the motor.

- (a) List methods of speed control of slip ring wound rotor induction moor. Give details of 10 6. each method.
 - (b) A 6 pole 50 Hz 3 phase slip ring a.c. induction motor is controlled using slip power recovery 10 scheme. If open circuit standstill voltage is 600 V and diode rectifier has overlap angle of 10 degrees determine angle of firing advance in the inverter if inverter is connected to 440 V.,3 phase line and overlap angle of inverter is 8 degrees. Motor speed is 600 RPM.
- 7. Write short notes on any three of the following :--
 - (a) Techniques of harmonic reduction in 3 phase inverters.
 - (b) Vector control of a.c. induction motor
 - (c) Stepper motor-construction, working and applications.
 - (d) Cyclo converter-working and applications.

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