

AGJ 1st half (f+) 37

Con. 9678-13.

(OLD COURSE)
(3 Hours)

GS-4978
[Total Marks : 100

- N.B. :** (1) Question No. 1 is compulsory.
(2) Solve any **four** questions out of remaining **six** questions.
(3) Assume **suitable** data wherever **necessary**.

1. (a) Explain MESI protocol used in pentium. 10
(b) For 16-bit device, explain data steering logic for pentium. 10
 2. (a) Explain pentium branch prediction logic. 10
(b) Explain various special cycles of pentium. 10
 3. (a) Draw and explain pentium Burst bus cycle with one wait state per Quadword. 10
(b) Explain code cache structure with split line access. 10
 4. (a) Master A wants to perform 2 transactions with 3 data phases and 1 data phase 10
respectively. Master B wants to perform only one transaction with one data phase.
Master A has already requested. Master B of higher priority is now requesting.
Explain with neat timing diagram, bus arbitration in PCI.
(b) Explain Bus Access Lathency in PCI. 10
 5. (a) Explain PCI signals :- 10
(i) $\overline{\text{FRAME}}$
(ii) $\overline{\text{PAR64}}$
(iii) $\overline{\text{LOCK}}$
(iv) $\overline{\text{SBO}}$
(v) $\overline{\text{TRDY}}$ 10
(b) In PCI, explain interrupt chaining process.
 6. (a) Explain following terms of USB bus - 10
(i) Host controller and its functions
(ii) NAK and ACK token
(iii) Transaction frame.
(b) Explain following signals in SCSI. 10
ATN, MSG, BSY, SEL
 7. (a) Explain protocol for data read/write commands in IDE. 10
(b) Explain Refleoted wave switching in PCI bus. 5
(c) What is sector interleave and its use. 5
-

N.B. : (1) Question No. 1 is compulsory.

(2) Attempt any four out of remaining six questions.

(3) Assume suitable data wherever necessary.

1. (a) Design a CMOS logic gate for the function :— 5

$$f = \overline{A + (B + C)(D + E)}$$
- (b) Compare ion implantation and diffusion. 5
- (c) Explain the flat band condition. 5
- (d) Explain channel length modulation of MOSFET. 5
2. (a) Calculate the zero bias threshold voltage for an NMOS silicon gate transistor that 10
 has well doping $N_A = 3 \times 10^{17} \text{ cm}^{-3}$, gate doping $N_D = 10^{20} \text{ cm}^{-3}$ gate oxide thickness
 $t_{\text{ox}} = 200 \text{ \AA}$ and $Q_{\text{ss}} = 2 \times 10^{10} \text{ cm}^{-2}$.
- (b) Explain latchup in CMOS and how to prevent it. 10
3. Draw a circuit diagram, stick diagram and layout. Using lambda based design rule. 20
4. (a) What is scaling. Explain constant voltage and constant field scaling in detail with their 10
 merits and demerits.
- (b) Compare resistive, enhancement, depletion load NMOS and CMOS inverter. 10
5. (a) Explain the complete fabrication process steps for a CMOS inverter using a n-well 10
 process (cross sectional view).
- (b) Explain CMOS design rule :— 10

(i) N. P Well	(iii) Poly
(ii) Active	(iv) Contact.
6. (a) Differentiate butting and buzzied contact. 10
- (b) Discuss the sizing of the various transistor in a four input NAND gate based on the 10
 reference inverter. In reference inverter $\frac{W}{L}$ ratio of the depletion load transistor is
 4/1 and the (W/L) of the driver transistor is 2/1. Also draw schematic.
7. Write short notes on :— 20
 (a) Hot electron effect
 (b) CZ method of water processing
 (c) MOS capacitor.

BE- (ELECT) SEM IV (old)
J.S.

14/5/13
May 2013

15 : 1st half.13-shilpa(i)

Con. 8299-13.

(OLD COURSE)

GS-4333

(3 Hours)

[Total Marks : 100

N.B. : (1) Question No. 1 is **compulsory**.

(2) Attempt any **four** questions out of remaining **six** questions.

(3) Assume suitable **data** wherever **required**.

(4) Illustrate answer with **sketches** wherever **required**.

(5) **Figures** to the **right** indicate **full marks**.

1. (a) Choose the most suitable temperature transducer for measuring the temperature 20
in each of the following :-
 - (i) Rapidly changing temperature
 - (ii) Very small temperature changes about 40°C
 - (iii) Very high temperature (> 1500°C)
 - (iv) Highly accurate temperature measurement
 - (v) Wide temperature variations.
 - (b) Describe the operation of a Piezo-electric transducer.
 - (c) What are the objectives of a DAS ?
 - (d) Define the following terms :-(any two)
 - (i) repeatability
 - (ii) rangeability
 - (iii) reproducibility
 - (iv) sensitivity.
-
2. (a) List different flow measuring devices, with a neat sketch, explain the operation 10
of a magnetic flowmeter. What are its advantages and limitations ?
 - (b) For the first order instrument, find the step response and ramp response. 10
-
3. (a) Explain the principle of Hall effect and how it can be used for measuring angular 10
displacement.
 - (b) Explain the operation of resistance strain gauges and hence derive the 10
expression for gauge factor.
-
4. (a) Discuss the Piezo-electric transducer with proper signal conditioning circuits 10
for vibration measurement.
 - (b) Explain briefly :— 10
 - (i) photo conductive cell
 - (ii) photo voltaic cell.
-
5. (a) What is LVDT ? Explain the use of phase sensitive detector for operation of 10
LVDT.
 - (b) Give different types of load cell configuration. Hence explain effect of 10
temperature variations for force measurement.

[TURN OVER

16 : 1st half.13-shilpa(i)

Con. 8299-GS-4333-13.

2

6. (a) Describe the Multichannel Analog Multiplexed Data Acquisition System. State its merit and demerits over Digital Multiplexing Data Acquisition System. **10**
- (b) Explain Absorbance type and Transmission type of Torque measurement. **10**
7. Write short notes on :- **20**
- (a) Virtual Instrumentation
 - (b) Optical Pyrometer
 - (c) Data logger.

21/5/2013

B.E (ETAX) for VIT (old)

Filter Theory & Application

3: 1ST HALF-13 (q)-JP

Con. 7751-13.

(OLD COURSE)

GS-4213

(3 Hours)

[Total Marks : 100

- N.B.** (1) Question No. 1 is **compulsory**.
(2) Attempt any **four** of the remaining **six** questions.
(3) Assume **suitable** additional data wherever **necessary**.

1. Answer the following :— 20

- (a) Compare FIR and IIR filters.
- (b) Compare rectangular and Hamming window with respect to main and side lobe characteristics.
- (c) Explain - 'Ideal filter characteristics are not realisable'.
- (d) Sketch the locations of all zeros of a linear phase FIR filter if the zeros are at $0.5 e^{j\pi/3}$ and 0.2 .

2. (a) The desired response of a low pass filter is - 15

$$H_D(e^{jw}) = \begin{cases} e^{-j3w} & |w| \leq \frac{3\pi}{4} \\ 0 & \text{otherwise} \end{cases}$$

(b) Explain the characteristics of different window functions. 5

3. (a) Prove that $S = \frac{2}{T} \left[\frac{1-z^{-1}}{1+z^{-1}} \right]$ and $w = 2 \tan^{-1} (\Omega T / 2)$ in Bilinear transformation. 15

Also explain mapping between s-plane and z-plane.

(b) Write a short note on the intuitive method of IIR filter design. 5

4. (a) Design a Butterworth filter using impulse invariance and Bilinear transformation 15
method for the following specifications. Assume $T = 1$ sec.

$$\begin{aligned} 0.8 \leq |H(e^{jw})| \leq 1 & \text{ for } 0 \leq |w| \leq 0.2\pi \\ |H(e^{jw})| \leq 0.2 & \text{ for } 0.6\pi \leq |w| \leq \pi \end{aligned}$$

(b) Prove that zeros in linear phase FIR filter occur at reciprocal location. 5

[TURN OVER

Con. 7751-GS-4213-13.

2

5. (a) Determine the coefficient of a linear phase FIR filter of length $M \neq 15$ having symmetric unit impulse response and frequency satisfying the following condition — **15**

$$H_v \left(\frac{2\pi k}{15} \right) = \begin{cases} 1 & k = 0, 1, 2, 3 \\ 0.4 & k = 4 \\ 0 & k = 5, 6, 7 \end{cases}$$

- (b) Write a short note on Gibbs phenomenon. **5**
6. (a) Explain digital filter design technique using Kaiser window. **10**
(b) Explain the impulse invariance technique of designing IIR filters. **10**
7. Write short notes on (any two) :— **20**
- (a) Analog frequency transformation
 - (b) Frequency warping effect on Bilinear transformation
 - (c) Limit cycle oscillation due to quantisation.
-

- N.B.** (1) Question No. 1 is compulsory.
 (2) Attempt any **four** questions out of remaining **six** questions.
 (3) Assume **suitable** data if **required** but justify the **same**.

1. Answer the following questions (any four) :— 20

- (a) Define random variables and differentiate between discrete and continuous random variables.
- (b) Show that entropy is maximum when all the messages are equiprobable.
- (c) Differentiate between offset and non-offset QPSK
- (d) Show that duobinary signaling suffers from error propagation while precoded duobinary signaling does not.
- (e) What is matched filter ? How it differs from optimum filter.

2. (a) A discrete memoryless channel has six symbol as shown with probabilities : 10

Message	M_1	M_2	M_3	M_4	M_5	M_6
Probability	0.3	0.25	0.2	0.12	0.08	0.05

Find the codewords, average no. of bits per message, code efficiency, redundancy and variance using Huffman coding.

(b) For a (7, 4) linear block code (hamming code) :— 10

- (i) Design Generator Matrix
- (ii) Find the code vectors for the message :—
 - (1) 0011
 - (2) 1010
- (iii) Write the Parity check matrix.
- (iv) Detect and correct the error of any in the following received code word :
 - (1) 0111100
 - (2) 0001001

3. (a) A convolutional encoder has following impulse response 12

$$G_1 = \{1, 1, 0\}, \quad G_2 = \{1, 1, 1\}, \quad G_3 = \{1, 0, 1\}$$

- (i) Sketch the encoder
- (ii) Find the code word for the message 11001
- (iii) Draw the code tree, state diagram and trallis diagram for the above codeword.

(b) Differentiate between :— 8

- (i) Source coding and channel coding
- (ii) Systematic and non-systematic cyclic code.

Con. 9206-GS-4633-13.**2**

4. (a) Draw the block diagram of BPSK modulator and demodulator and describe the following :— **10**
- (i) Distance between two transmitted symbol and effect of noise
 - (ii) Power spectral density and hence bandwidth for BPSK.
- (b) Differentiate between :— **10**
- (i) MPSK and MFSK
 - (ii) Duobinary encoding and modified duobinary encoding.
5. (a) Why MSK is called shaped QPSK ? Justify with relevant waveform. **10**
- (b) Prove that for the 16-ary QASK digital modulation techniques, the Euclidian distance is given by – **10**
- $$d = 2 \sqrt{0.4 E_b}$$
6. (a) Draw the block diagram of DS-SSS transmitter and receiver. Obtain the expression for the signal at the output of each block and show that the original sequence can be recovered at the receiver output. **10**
- (b) What are Pseudo-noise sequence in spread spectrum technology ? Why they are used in spread spectrum modulation ? Draw a neat diagram to generate a P-N sequence (assume any No.) **10**
7. Write short notes on the following (any four) :— **20**
- (a) ISI and Eye diagram
 - (b) Tapped-delay line equalizer
 - (c) Nyquist criteria for distributionless baseband signal
 - (d) Central limit theorem
 - (e) Lempel ziv coding with suitable example.
-