

1615/17

M.E (EXTC) - sem-I
(Choice-based)

03

QP Code : 841900

Statistical Signal Processing

(3 Hours)

[Total Marks : 80

- N.B. :** (1) Question No. 1 is compulsory.
 (2) Attempt any three questions from the remaining five questions.
 (3) Assume **suitable data** if needed and state it clearly.
 (4) Figures to right indicate full marks.

1. Attempt **any five** :

- (a) Find the nullspace of 4

$$A = \begin{bmatrix} -3 & 6 & -1 & 1 & -7 \\ 1 & -2 & 2 & 3 & -1 \\ 2 & -4 & 5 & 8 & -4 \end{bmatrix}$$

- (b) Explain the application of Discrete KL Transform in data compression. 4
 (c) Derive an expression for mean value of the output of an LTI system when input is WSS process. 4
 (d) Define and explain Skewness and Kurtosis. 4
 (e) State the CRLB theorem. 4
 (f) State the Kalman filtering problem. 4
2. (a) Define Metric, Metric space, Norm, Induced norm. Vector space and state its properties. 5
 (b) Construct an orthonormal basis of \mathbb{R}^3 using Gram-Schmidt orthogonalisation for the set of vectors $u_1 = (1, 2, 2)$, $u_2 = (-1, 0, 2)$ and $u_3 = (0, 0, 1)$. 10
 (c) State the SVD theorem and explain its applications. 5
3. (a) State the central limit theorem 5
 (b) Find mean, variance and characteristic function of uniform Random variable. 7
 (c) Let $Y=W+X$, where W and X are independent random variables. 8
 Derive an expression for the pdf of Y .
4. (a) For $x(n) = A+w(n)$ $n= 0,1,\dots,N-1$ where $w(n)$ is WGN with zero mean and variance σ^2 . Determine the CRLB for a DC level A . 12
 (b) Define and explain bias of estimator, consistent estimator, minimum variance unbiased estimator and efficient estimator. 8

[TURN OVER]

5. (a) Consider a transformation $\mathbf{y} = \mathbf{Q}^H \mathbf{x}$, where \mathbf{Q} is an eigen matrix and \mathbf{H} denotes Hermitian. Find the mean and autocorrelation of \mathbf{y} . It is given that \mathbf{x} is a zero mean random vector with correlation matrix. 10

$$\mathbf{R}_x = \begin{bmatrix} 1 & 0.5 \\ 0.5 & 1 \end{bmatrix}$$

- (b) Explain LDU decomposition of an autocorrelation matrix \mathbf{R} and also explain its linear filtering interpretation. 10
6. (a) Explain in detail Kalman Filter I- Bayes Approach 10
(b) Write short note on Positive definite matrices 5
(c) State and explain Applications of Estimation theory. 5
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