Sem-V (Sem IV OTR) - EXTC

D+15/6/17

Q. P. Code: 586502

02

Maximum Marks: 100 Duration: 3 Hrs

N.B.: - i) Question No. 1 is compulsory.

- ii) Answer any four questions out of remaining six questions.
- iii) Figure to the right indicates full marks.
- iv) Illustrate the answers with sketches wherever required.

Q.1. Solve any four

20M

a) Draw even and odd part of the following signals

i)
$$x(t) = 2 r(t) - 2 r(t-1) - 2 u(t-3)$$

ii)
$$x(t) = u(t) - r(t) + 2 r(t-2) - r(t-3) + u(t-4) - 2u(t-5)$$

b) Explain whether the following signals are power signals or energy signals

i)
$$x(t) = 0.9e^{-3t} u(t)$$

ii)
$$x(t) = Asint$$

- c) List the properties of Laplace transform.
- d) Perform convolution of the following continuous time system using Laplace transform 2u(t) with u(t).
- e) Find impulse response and plot $H(z) = \frac{2}{1 + 2Z^{-1}}$, |z| < 2

Q. 2

a) Find the even and odd components of
i) x(t) = sin2t + cost + sint.cost

8M

ii)
$$x(t) = t^3 + 3t$$

b) Convolute $x(n) = (1/3)^n u(n)$ with $h(n) = (1/2)^n$ using convolution sum formula and verify using Z transform

6M

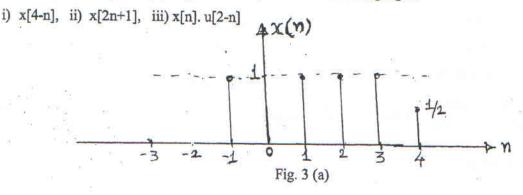
c) Sketch the following signal : x(t) = 2 u(t) + 2 u(t-2) - 2 u(t-4) - 2 u(t-6)

6M

Q.3.

a) Referring to the Figure 3 (a) as given below, sketch the following signal

9M



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b) State and prove frequency shift property of Fourier transform

5M

c) List whether the following system is Dynamic, Causal, Linear, Time Invariant

6M

- i) $y(t) = x(t^2)$
- ii) $y(t) = x(t) \cdot \cos(100\pi t)$

Q.4.

a) Draw the Direct Form structure of the FIR system described by the transfer function

$$H(Z) = 1 + \frac{1}{2}Z^{-1} + \frac{3}{4}Z^{-2} + \frac{1}{4}Z^{-3} + \frac{1}{2}Z^{-4} + \frac{1}{8}Z^{-5}$$

b) What are the properties of ROC in Z-transform?

4M

c) Obtain Direct Form-I, Direct Form-II realization of the LTI system governed by equation

6M

$$y(n) = x(n) + 0.5 x(n-1) + 0.4 x(n-2) - 0.6 y(n-1) - 0.7 y(n-2)$$

Q. 5.

A system has the following system function

10M

$$H(z) = \frac{1}{(z - 0.25)(z - 0.5)}$$

- i) Find the impulse response of the system if the system is stable
- ii) Find the step response of the system

b) Using Z transform solve the difference equation and find out impulse

5M

$$y[n] - 2y[n-1] + y[n-2] = x[n] + 3x[n-3]$$

c) Derive relationship between Z-transform and Fourier Transform

5M

Q. 6.

response of

a) Consider a continuous time LTI system described by $\frac{d(y(t))}{dt} + 2y(t) = x(t)$. Using 6M

Fourier transform find the o/p to each of the following input i) $x(t) = e^{-t} u(t)$, ii) x(t) = u(t).

b) Determine the state model of the system governed by equation

4M

$$y(n) = -2 y(n-1) + 2 y(n-2) + 0.5 y(n-3) + 2 x(n) + 1.5 x(n-1) + 2.5 x(n-2) + 4 x(n-3)$$

c) Find the system output of a system having differential equation

10M

$$\frac{d^2y(t)}{dt^2} + \frac{5dy(t)}{dt} + 6y(t) = \frac{dx(t)}{dt} + x(t)$$

With initial condition y(0) = 2; $\frac{dy(y)}{dt} = 1$; $x(t) = e^{-4t}u(t)$

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Q.7.

a) The State model of a discrete time system is given by

7M

$$A = \begin{bmatrix} 2 & 0 \\ 3 & 1 \end{bmatrix}; B = \begin{bmatrix} 1 \\ 2 \end{bmatrix}; C = \begin{bmatrix} 1 & 3 \end{bmatrix}; D = 3$$

Find the response of the discrete time system for the unit step input. Assume zero initial condition

b) Realize the given system in cascade and parallel form

7M

$$H(z) = \frac{\left(1 + \frac{1}{2}z^{-1}\right)}{\left(1 - z^{-1} + \frac{1}{4}z^{-2}\right)\left(1 - z^{-1} + \frac{1}{2}z^{-2}\right)}$$

c) If the system matrix $A = \begin{bmatrix} -3 & 0 \\ 0 & -2 \end{bmatrix}$, Find the state transition matrix of discrete time 6M System.